

Likelihood Ratios

It's from Radon-Nikodym Thm. — change measure.

e.g. in c.n. $\mathcal{B}$, P_1, P_2 are prob. measure s.t. $P_1 \ll P_2$.

Then for r.v. X : $E_{P_1}(X) = E_{P_2}(X L)$. $L = \frac{dP_1}{dP_2}$

Applications:

① Monte Carlo:

To estimate the prob of an event. The accuracy depends on the frequency of the event.

e.g. For $X \stackrel{P_0}{\sim} N(0, 1)$: $P_0(X > 2.5)$ is small. So

$\{X > 2.5\}$ seldom occurs under P_0 . but if consider:

$$E_0(I_{\{X > 2.5\}}) = E_{2.5}(L(X) I_{\{X > 2.5\}})$$

$$L(x) = f_0(x) / f_{2.5}(x) = \frac{\frac{1}{\sqrt{2\pi}} e^{-\frac{x^2}{2}}}{\frac{1}{\sqrt{2\pi}} e^{-\frac{(x-2.5)^2}{2}}} = e^{-2.5x + \frac{25}{2}}$$

$X \sim N(2.5, 1)$ under $dP_{2.5} = f_{2.5} dX$.

$\Rightarrow$ Estimated by: $\frac{\sum_{i=1}^n L(x_i) I_{\{X > 2.5\}}(x_i)}{n}$.

② Gambler's Ruin:

Suppose $X_k \stackrel{i.i.d}{\sim} N(m, 1)$. $S_n = \sum_{i=1}^n X_k$. $m_1 < 0$

$$\tau_b = \min \{n \mid S_n > b\}.$$

prop. $P_{m_1}(Z_b < \infty) \leq e^{-2mb}$.

Pf. Note $RHS = P_{m_1}(\tilde{Z}_b < \infty)$, $\tilde{Z}_b = \inf\{t \mid X(t) = b\}$.

where $X(t) = m_1 t + W(t)$.

Next, prove: $P_{m_1}(Z_b = \infty) \geq P_{m_1}(\tilde{Z}_b = \infty)$

Note $X(n) \sim S_n \sim N(nm_1, n)$ $n \in \mathbb{Z}^+$.

$$\begin{aligned} RHS &= P(\forall t \geq 0, X(t) < b) \leq P_{m_1}(\forall n \in \mathbb{Z}^+, X(n) < b) \\ &= P_{m_1}(\forall n \in \mathbb{Z}^+, S_n < b) \\ &= P_{m_1}(Z_b = \infty) \end{aligned}$$

Note: $X_k \stackrel{P_1}{\sim} N(m_1, 1)$, $X_k \stackrel{P_2}{\sim} N(m_2, 1)$. Then: we have.

$$L(\vec{x}) = \lambda P_1 / \lambda P_2 = e^{-\frac{1}{2} \sum_{i=1}^n (x_i - m_1)^2} / e^{-\frac{1}{2} \sum_{i=1}^n (x_i - m_2)^2} \text{ for } \vec{x} = (x_1, \dots, x_n)$$

$$P_{m_1}(B(x_1, \dots, x_n)) = E_{m_1}(L(\vec{x}) I_B).$$

Next, we will extend "n" to stopping time τ :

Def. i) $\mathcal{G}_n = \{Y \mid Y = h(x_1, \dots, x_n)\}$.

ii) $\mathcal{G}_\tau = \{Y \mid Y I_{\tau \leq n} \in \mathcal{G}_n, \forall n\}$. τ is a stopping time.

Thm. (Wald's LR Identity)

$Y \in \mathcal{G}_\tau$. b.l.a. If $(x_1, \dots, x_n) \stackrel{P_i}{\sim} f_i^n$, $i = 1, 2$.

$$L_n = f_1^n / f_2^n. \text{ Then: } E_1(Y I_{\tau \leq n}) = E_2(Y L_\tau I_{\tau \leq n})$$

$$\begin{aligned} \text{Pf: } LHS &= \sum E_1(Y I_{\tau \leq n}) \\ &= \sum E_2(Y I_{\tau \leq n} L_n) \\ &= \sum E_2(Y I_{\tau \leq n} L_\tau) \\ &= E_2(Y L_\tau I_{\tau < \infty}) \end{aligned}$$

i) Apply on Z_b . Set $m_2 = -m_1$. $B = \{Z_b < -\}$.

$$\begin{aligned} \text{Then: } P_{m_1}(Z_b < -) &= E_2(e^{2m_1 Z_b} I_{\{Z_b < -\}}) \\ &\leq e^{2m_1 b} \text{ directly.} \end{aligned}$$

ii) Consider $T = Z_a \wedge Z_b$. $B = \{S_T > b\}$. $m_2 = -m_1$.

$$\begin{aligned} \text{Then: } P_{m_1}(S_T > b) &= E_{m_2}(e^{2m_1 S_T} I_{\{S_T > b\}}) \\ &= e^{2m_1 b} E_{m_1}(e^{2m_1 R_b} I_{\{S_T > b\}}) \end{aligned}$$

$R_b = S_{Z_b} - b$. $e^{2m_1 b}$ is small which will influence accuracy if we want to simulate S_T .

③ Brownian Motion:

Def: $\mathcal{F}_2 = \{Y \mid Y I_{\{Z \leq t_3\}} \in \mathcal{F}_t, \forall t \geq 0\}$.

$\mathcal{F}_t = \{Y \mid Y = h(\langle W \rangle_0^t)\}$, for process $(W_t)_{t \geq 0}$.

For $0 = t_0 < t_1 < \dots < t_n = t$. if $W_t \stackrel{P_i}{\sim} N(m_i t, t)$, $i = 1, 2$.

$$\begin{aligned} P_{m_1}(W(t_i) \in A_{W_i}, 1 \leq i \leq n) / P_{m_2}(W(t_i) \in A_{W_i}, 1 \leq i \leq n) \\ = \exp(-\frac{1}{2} \sum_{i=1}^n \frac{1}{t_i - t_{i-1}} (W_i - W_{i-1} - m_i(t_i - t_{i-1}))^2) / \square_{m_1} = e^{(m_1 - m_2)W_t - \frac{t}{2}(m_1^2 - m_2^2)} \end{aligned}$$

To obtain L_t . Set $n \rightarrow \infty$ to approxi. by finite set

$$\Rightarrow L_t = \exp((m_1 - m_2)W(t) - \frac{t}{2}(m_1^2 - m_2^2))$$

prop. $Y \geq 0$. $Y \in \mathcal{F}_2$. $E_{m_1}(Y I_{\{Z < -\}}) = E_{m_2}(Y L_2 I_{\{Z < -\}})$

Pf: Set $Z_n = \lfloor 2^n Z \rfloor + 1/2^n$. Obtain equation
Let $n \rightarrow \infty$ by MCT. ($Y \geq 0$)

i) For $b > 0, m > 0, M_1 = -m = -M_2, \forall Y \in \mathcal{F}_{2b}$.

$$\begin{aligned} E_{-m}(Y | \mathcal{F}_{2b \leftarrow 3}) &= E_m(Y e^{-2mV(2b)} | \mathcal{F}_{2b \leftarrow 3}) \\ &= e^{-2mb} E_m(Y | \mathcal{F}_{2b \leftarrow 3}) \end{aligned}$$

By $P_m(z_b \leftarrow) = 1$ ($m > 0$), $RHS = e^{-2mb} E_m(Y)$.

$$\Rightarrow E_{-m}(Y | z_b \leftarrow) = E_{-m}(Y I_0) / P_{-m}(z_b \leftarrow) = E_m(Y)$$

Set $Y = \{z_b \leq t\}$. So: $P_{-m}(z_b \leq t | z_b \leftarrow) = P_m(z_b \leq t)$

i.e. drift $-m$ of $z_b | z_b \leftarrow \sim$ drift m of z_b

ii) From i), and reflection Principle. We have:

$$P_{-m}(z_b \leq t) = 1 - \phi\left(\frac{b+mt}{\sqrt{t}}\right) + e^{-2mb} \phi\left(\frac{-b+mt}{\sqrt{t}}\right). \text{ It's called inverse Gaussian dist. } (W_t \stackrel{P_m}{\sim} N(-mt, t))$$

$$LHS = P_{-m}(z_b \leq t, W_t \geq b) + P_{-m}(z_b \leq t, W_t \leq b)$$

$$1') P_{-m}(z_b \leq t, W_t \geq b) = P_{-m}(W_t \geq b) = 1 - \phi\left(\frac{b+mt}{\sqrt{t}}\right)$$

$$2') P_{-m}(z_b \leq t, W_t \leq b) = \int_0^t P_{-m}(W_t \leq b | z_b = s) P_{-m}(z_b \leq ds)$$

$$P_{-m}(W_t \leq b | z_b = s) \stackrel{MP}{=} P_{-m}(W_t \leq b | W_s = b)$$

$$= P(N(-m(t-s), t-s) \leq 0)$$

$$= P(N(m(t-s), t-s) \geq 0)$$

$$\stackrel{MP}{=} P_m(W_t \geq b | z_b = s)$$

combined with: $P_{-m}(z_b \leq ds) = e^{-2mb} P_m(z_b \leq ds)$

follows from i).